About P4: Put all the code together, build your pipeline and print / show out all the important outputs, variables and images to check if the code is returning the expected, ok?

Do it and you will see where you need to improve the code.

Use the forum a lot!!! We are having discussion there about this project, ok?

**IMAGE CALIBRATION**

Image calibration will set the image correction coefficients. Coefficients are common to all images. It is necessary to calibrate with several images to calculate these coefficients. Theoretically, you can do with 1 image, but the more images the more assertive your calculation will be. It is required not only for lane but for all sorts of image analysis you will do in the future.

**ARTICLES**

* [**Advanced Lane Line Project**](https://chatbotslife.com/advanced-lane-line-project-7635ddca1960)
* [**More robust lane finding using advanced computer vision techniques**](https://chatbotslife.com/robust-lane-finding-using-advanced-computer-vision-techniques-46875bb3c8aa)

**PROJECT Q&A**

Join Udacity Self-Driving Car Nanodegree instructors as they guide you through project roadblockers and answer your questions live! (RECORDED)

* [**Self-Driving Car Project Q&A | Advanced Lane Finding**](https://www.youtube.com/watch?v=vWY8YUayf9Q&list=PLAwxTw4SYaPkz3HerxrHlu1Seq8ZA7-5P&index=4)